

A Lego Mindstorms Maze Solving Robot

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Next Wave in Robotics - Tzoo-Hseng S. Li 2011-08-25

This book constitutes the refereed proceedings of the 14th RoboWorld Cup and Congress of the Federation of International Robosoccer Association, FIRA 2011, held in Kaohsiung, Taiwan in August 2011. The 34 revised papers presented were carefully reviewed and selected for inclusion in the proceedings out of a total of 110 contributed papers presented at FIRA 2011. The papers address a broad variety of current topics in robotics research, particularly in robot soccer.

Winning LEGO MINDSTORMS Programming - James Trobaugh 2012-12-22

Winning LEGO MINDSTORMS Programming is your ticket to successfully programming for fun and competition with LEGO MINDSTORMS and the NXT-G programming language commonly used in FIRST LEGO League events. The book is a companion title to author James Trobaugh's acclaimed book on physical robot design, *Winning Design!*. This new book focuses squarely on the programming side of working with MINDSTORMS. Together the two books put you on a rock-solid foundation for creating with LEGO MINDSTORMS, whether for fun at home or in competition with a team. *Winning LEGO MINDSTORMS Programming* sets the stage by emphasizing the importance of up front planning, and thinking about the challenge to be met. Learn to evaluate possible solutions by sanity-testing their logic before you put the effort into actually writing the code. Then choose your best option and write the code applying the techniques in this book. Take advantage of language features such as MyBlocks to enhance reliability and create easy-to-debug code. Manage your code as you change and improve it so that you can trace what you've done and fall back if needed. Avoid common programming pitfalls. Work powerfully with teammates to conquer competition challenges of all types. Provides solid techniques similar to those used by professional programmers, and optimized for the LEGO MINDSTORMS platform. Addresses key tasks important to competition such as line detection, line following, squaring of corners, motor stall detection, and more. Compliments *Winning Design!* by tackling the programming side of competition.

LEGO MINDSTORMS NXT 2.0 - James Floyd Kelly 2010-01-13

Follow the adventures of Evan and his archaeologist uncle as they explore for treasure from an ancient kingdom. Help them succeed by building a series of five robots using LEGO's popular MINDSTORMS NXT 2.0 robotics kit. Without your robots, Evan and his uncle are doomed to failure and in grave danger. Your robots are the key to their success in unlocking the secret of The King's Treasure! In this sequel to the immensely popular book, *LEGO MINDSTORMS NXT: The Mayan Adventure*, you get both an engaging story and a personal tutorial on robotics programming. You'll learn about the motors and sensors in your NXT 2.0 kit. You'll learn to constructively brainstorm solutions to problems. And you'll follow clear, photo-illustrated instructions that help you build, test, and operate a series of five robots corresponding to the five challenges Evan and his uncle must overcome in their search for lost treasure. Provides an excellent series of parent/child projects Builds creative and problem-solving skills Lays a foundation for success and fun with LEGO MINDSTORMS NXT 2.0 Please note: the print version of this title is black & white; the eBook is full color.

Intelligent Robotics and Applications - Jangmyung Lee 2013-08-23

This two volume set LNAI 8102 and LNAI 8103 constitutes the refereed proceedings of the 6th International Conference on Intelligent Robotics and Applications, ICIRA 2013, held in Busan, South Korea, in September 2013. The 147 revised full papers presented were carefully reviewed and selected from 184 submissions. The papers discuss various topics from intelligent robotics, automation and mechatronics with particular emphasis on technical challenges associated with varied applications such as biomedical application, industrial automation, surveillance and sustainable mobility.

Robot Building for Beginners - David Cook 2010-07-30

"I wrote this book because I love building robots. I want you to love building robots, too. It took me a while to learn about many of the tools and parts in amateur robotics. Perhaps by writing about my experiences, I can give you a head start." —David Cook *Robot Building for Beginners, Second Edition* is an update of David Cook's best-selling *Robot Building for Beginners*. This book continues its aim at teenagers and adults who have an avid interest in science and dream of building household explorers. No formal engineering education is assumed. The robot described and built in this book is battery powered and about the size of a lunchbox. It is autonomous. That is, it isn't remote controlled. You'll begin with some tools of the trade, and then work your way through prototyping, robot bodybuilding, and eventually soldering your own circuit boards. By the book's end, you will have a solid amateur base of understanding so that you can begin creating your own robots to vacuum your house or maybe even rule the world!

Research Anthology on Computational Thinking, Programming, and Robotics in the Classroom - Management Association, Information Resources 2021-07-16

The education system is constantly growing and developing as more ways to teach and learn are implemented into the classroom. Recently, there has been a growing interest in teaching computational thinking with schools all over the world introducing it to the curriculum due to its ability to allow students to become proficient at problem solving using logic, an essential life skill. In order to provide the best education possible, it is imperative that computational thinking strategies, along with programming skills and the use of robotics in the classroom, be implemented in order for students to achieve maximum thought processing skills and computer competencies. The *Research Anthology on Computational Thinking, Programming, and Robotics in the Classroom* is an all-encompassing reference book that discusses how computational thinking, programming, and robotics can be used in education as well as the benefits and difficulties of implementing these elements into the classroom. The book includes strategies for preparing educators to teach computational thinking in the classroom as well as design techniques for incorporating these practices into various levels of school curriculum and within a variety of subjects. Covering topics ranging from decomposition to robot learning, this book is ideal for educators, computer scientists, administrators, academicians, students, and anyone interested in learning more about how computational thinking, programming, and robotics can change the current education system.

The Art of LEGO MINDSTORMS EV3 Programming - Terry Griffin 2014-10-01

With its colorful, block-based interface, The LEGO® MINDSTORMS® EV3 programming language is designed to allow anyone to program intelligent robots, but its powerful features can be intimidating at first. *The Art of LEGO MINDSTORMS EV3 Programming* is a full-color, beginner-friendly guide designed to bridge that gap. Inside, you'll discover how to combine core EV3 elements like blocks, data wires, files, and variables to create sophisticated programs. You'll also learn good programming practices, memory management, and helpful debugging strategies—general skills that will be relevant to programming in any language. All of the book's programs work with one general-purpose test robot that you'll build early on. As you follow along, you'll program your robot to: -React to different environments and respond to commands -Follow a wall to navigate a maze -Display drawings that you input with dials, sensors, and data wires on the EV3 screen -Play a Simon Says-style game that uses arrays to save your high score -Follow a line using a PID-type controller like the ones in real industrial systems *The Art of LEGO MINDSTORMS EV3 Programming* covers both the Home and Education Editions of the EV3 set, making it perfect for kids, parents, and teachers alike. Whether your robotics lab is the living room or the classroom, this is the complete guide to EV3 programming that

you've been waiting for. Requirements: One LEGO MINDSTORMS EV3 Home OR Education set (#31313 OR #45544).

Advances in Autonomous Robotics - Guido Herrmann 2012-07-25

This book constitutes the refereed proceedings of the 13th Conference on Towards Autonomous Robotic Systems, TAROS 2012 and the 15th Robot World Congress, FIRA 2012, held as joint conference in Bristol, UK, in August 2012. The 36 revised full papers presented together with 25 extended abstracts were carefully reviewed and selected from 89 submissions. The papers cover various topics in the field of autonomous robotics.

Computational Thinking in the STEM Disciplines - Myint Swe Khine 2018-08-14

This book covers studies of computational thinking related to linking, infusing, and embedding computational thinking elements to school curricula, teacher education and STEM related subjects. Presenting the distinguished and exemplary works by educators and researchers in the field highlighting the contemporary trends and issues, creative and unique approaches, innovative methods, frameworks, pedagogies and theoretical and practical aspects in computational thinking. A decade ago the notion of computational thinking was introduced by Jeannette Wing and envisioned that computational thinking will be a fundamental skill that complements to reading, writing and arithmetic for everyone and represents a universally applicable attitude. The computational thinking is considered a thought processes involved in a way of solving problems, designing systems, and understanding human behaviour. Assimilating computational thinking at young age will assist them to enhance problem solving skills, improve logical reasoning, and advance analytical ability - key attributes to succeed in the 21st century. Educators around the world are investing their relentless effort in equipping the young generation with real-world skills ready for the demand and challenges of the future. It is commonly believed that computational thinking will play a pivotal and dominant role in this endeavour. Wide-ranging research on and application of computational thinking in education have been emerged in the last ten years. This book will document attempts to conduct systematic, prodigious and multidisciplinary research in computational thinking and present their findings and accomplishments.

Interdisciplinary Mechatronics - M. K. Habib 2013-05-06

Mechatronics represents a unifying interdisciplinary and intelligent engineering science paradigm that features an interdisciplinary knowledge area and interactions in terms of the ways of work and thinking, practical experiences, and theoretical knowledge. Mechatronics successfully fuses (but is not limited to) mechanics, electrical, electronics, informatics and intelligent systems, intelligent control systems and advanced modeling, intelligent and autonomous robotic systems, optics, smart materials, actuators and biomedical and biomechanics, energy and sustainable development, systems engineering, artificial intelligence, intelligent computer control, computational intelligence, precision engineering and virtual modeling into a unified framework that enhances the design of products and manufacturing processes. Interdisciplinary Mechatronics concerns mastering a multitude of disciplines, technologies, and their interaction, whereas the science of mechatronics concerns the invention and development of new theories, models, concepts and tools in response to new needs evolving from interacting scientific disciplines. The book includes two sections, the first section includes chapters introducing research advances in mechatronics engineering, and the second section includes chapters that reflects the teaching approaches (theoretical, projects, and laboratories) and curriculum development for under- and postgraduate studies. Mechatronics engineering education focuses on producing engineers who can work in a high-technology environment, emphasize real-world hands-on experience, and engage in challenging problems and complex tasks with initiative, innovation and enthusiasm.

Contents: 1. Interdisciplinary Mechatronics Engineering Science and the Evolution of Human Friendly and Adaptive Mechatronics, Maki K. Habib. 2. Micro-Nanomechatronics for Biological Cell Analysis and Assembly, Toshio Fukuda, Masahiro Nakajima, Masaru Takeuchi, Tao Yue and Hiroataka Tajima. 3. Biologically Inspired CPG-Based Locomotion Control System of a Biped Robot Using Nonlinear Oscillators with Phase Resetting, Shinya Aoi. 4. Modeling a Human's Learning Processes toward Continuous Learning Support System, Tomohiro Yamaguchi, Kouki Takemori and Keiki Takadama. 5. PWM Waveform Generation Using Pulse-Type Hardware Neural Networks, Ken Saito, Minami Takato, Yoshifumi Sekine and Fumio Uchikoba. 6. Parallel Wrists: Limb Types, Singularities and New Perspectives, Raffaele Di Gregorio. 7. A Robot-Assisted Rehabilitation System - RehabRoby, Duygun Erol Barkana and

Fatih Özkul. 8. MIMO Actuator Force Control of a Parallel Robot for Ankle Rehabilitation, Andrew Mcdaid, Yun Ho Tsoi and Shengquan Xie. 9. Performance Evaluation of a Probe Climber for Maintaining Wire Rope, Akihisa Tabata, Emiko Hara and Yoshio Aoki. 10. Fundamentals on the Use of Shape Memory Alloys in Soft Robotics, Matteo Cianchetti. 11. Tuned Modified Transpose Jacobian Control of Robotic Systems, S. A. A. Moosavian and M. Karimi. 12. Derivative-Free Nonlinear Kalman Filtering for PMSG Sensorless Control, Gerasimos Rigatos, Pierluigi Siano and Nikolaos Zervos. 13. Construction and Control of Parallel Robots, Moharam Habibnejad Korayem, Soleiman Manteghi and Hami Tourajizadeh. 14. A Localization System for Mobile Robot Using Scanning Laser and Ultrasonic Measurement, Kai Liu, Hongbo Li and Zengqi Sun. 15. Building of Open-Structure Wheel-Based Mobile Robotic Platform, Aleksandar Rodic and Ivan Stojkovic. 16. Design and Physical Implementation of Holonomous Mobile Robot-Holbos, Jasmin Velagic, Admir Kaknjo, Faruk Dautovic, Muhidin Hujdur and Nedim Osmic. 17. Advanced Artificial Vision and Mobile Devices for New Applications in Learning, Entertainment and Cultural Heritage Do
The LEGO MINDSTORMS NXT 2.0 Discovery Book - Laurens Valk 2010-04-01

Discover the many features of the LEGO® MINDSTORMS® NXT 2.0 set. The LEGO MINDSTORMS NXT 2.0 Discovery Book is the complete, illustrated, beginner's guide to MINDSTORMS that you've been looking for. The crystal clear instructions in the Discovery Book will show you how to harness the capabilities of the NXT 2.0 set to build and program your own robots. Author and robotics instructor Laurens Valk walks you through the set, showing you how to use its various pieces, and how to use the NXT software to program robots. Interactive tutorials make it easy for you to reach an advanced level of programming as you learn to build robots that move, monitor sensors, and use advanced programming techniques like data wires and variables. You'll build eight increasingly sophisticated robots like the Strider (a six-legged walking creature), the CCC (a climbing vehicle), the Hybrid Brick Sorter (a robot that sorts by color and size), and the Snatcher (an autonomous robotic arm). Numerous building and programming challenges throughout encourage you to think creatively and to apply what you've learned as you develop the skills essential to creating your own robots. Requirements: One LEGO MINDSTORMS NXT 2.0 set (#8547) Features: -A complete introduction to LEGO MINDSTORMS NXT 2.0 -Building and programming instructions for eight innovative robots -50 sample programs and 72 programming challenges (ranging from easy to hard) encourage you to explore newly learned programming techniques -15 building challenges expand on the robot designs and help you develop ideas for new robots Who is this book for? This is a perfect introduction for those new to building and programming with the LEGO MINDSTORMS NXT 2.0 set. The book also includes intriguing robot designs and useful programming tips for more seasoned MINDSTORMS builders.

STEAM Meets Story - Gloria D. Campbell-Whatley 2021-06-11

This innovative STEAM guide will help general and special education teachers to increase effective instruction with adolescents (grades 5-10). The authors show teachers how to link STEM concepts with popular fiction and film selections as a catalyst to launch student interactions, discussions, projects, and investigations. This approach will promote problem solving and reasoning skills by initiating the scientific process, rather than simply presenting established facts. The book includes a wealth of lesson plans that connect abstract STEM ideas to realistic experiences that students encounter. Sample lessons call on students to produce drawings and models that move STEM to STEAM. Grounded in popular film and some of the most-read young adult books, the text includes teaching strategies found to be effective with traditionally underserved students and those with disabilities. Book Features: Standards-based STEM lessons interrelated and interwoven with writing, reading, speaking, and other skills. Practical ideas and hands-on activities for engaging adolescents in both traditional and virtual environments. Guidance for working with diverse populations, such as students with different abilities, culturally and linguistically diverse students, translingual students, and transnational students. Templates, handouts, and lessons linked to Star Wars, The Giver, The Immortal Life of Henrietta Lacks, Harry Potter, To Kill a Mockingbird, Star Trek, The Matrix, Holes, and more.

Educational Robotics in the Context of the Maker Movement - Michele Moro 2019-12-24

This book gathers papers presented at the International Conference "Educational Robotics in the Maker Era - EDUROBOTICS 2018", held in

Rome, Italy, on October 11, 2018. The respective chapters explore the connection between the Maker Movement on the one hand, and Educational Robotics, which mainly revolves around the constructivist and constructionist pedagogy, on the other. They cover a broad range of topics relevant for teacher education and for designing activities for children and youth, with an emphasis on using modern low-cost technologies (including block-based programming environments, Do-It-Yourself electronics, 3D printed artifacts, intelligent distributed systems, IoT technology and gamification) in formal and informal education settings. The twenty contributions collected here will introduce researchers and practitioners to the latest advances in educational robotics, with a focus on science, technology, engineering, arts and mathematics (STEAM) education. Teachers and educators at all levels will find valuable insights and inspirations into how educational robotics can promote technological interest and 21st century skills - e.g. creativity, critical thinking, teamwork, and problem-solving - with a special emphasis on new making technologies.

From AI to Robotics - Arkapravo Bhaumik 2018-02-28

From AI to Robotics: Mobile, Social, and Sentient Robots is a journey into the world of agent-based robotics and it covers a number of interesting topics, both in the theory and practice of the discipline. The book traces the earliest ideas for autonomous machines to the mythical lore of ancient Greece and ends the last chapter with a debate on a prophecy set in the apparent future, where human beings and robots/technology may merge to create superior beings - the era of transhumanism. Throughout the text, the work of leading researchers is presented in depth, which helps to paint the socio-economic picture of how robots are transforming our world and will continue to do so. This work is presented along with the influences and ideas from futurists, such as Asimov, Moravec, Lem, Vinge, and of course Kurzweil. The book furthers the discussion with concepts of Artificial Intelligence and how it manifests in robotic agents. Discussions across various topics are presented in the book, including control paradigm, navigation, software, multi-robot systems, swarm robotics, robots in social roles, and artificial consciousness in robots. These discussions help to provide an overall picture of current day agent-based robotics and its prospects for the future. Examples of software and implementation in hardware are covered in Chapter 5 to encourage the imagination and creativity of budding robot enthusiasts. The book addresses several broad themes, such as AI in theory versus applied AI for robots, concepts of anthropomorphism, embodiment and situatedness, extending theory of psychology and animal behavior to robots, and the proposal that in the future, AI may be the new definition of science. Behavior-based robotics is covered in Chapter 2 and retells the debate between deliberative and reactive approaches. The text reiterates that the effort of modern day robotics is to replicate human-like intelligence and behavior, and the tools that a roboticist has at his or her disposal are open source software, which is often powered by crowd-sourcing. Open source meta-projects, such as Robot Operating System (ROS), etc. are briefly discussed in Chapter 5. The ideas and themes presented in the book are supplemented with cartoons, images, schematics and a number of special sections to make the material engaging for the reader. Designed for robot enthusiasts - researchers, students, or the hobbyist, this comprehensive book will entertain and inspire anyone interested in the exciting world of robots.

Professional Microsoft Robotics Developer Studio - Kyle Johns 2009-02-10

Microsoft Robotics Developer Studio (MRDS) offers an exciting new way to program robots in the Windows environment. With key portions of the MRDS code available in source form, it is readily extensible and offers numerous opportunities for programmers and hobbyists. This comprehensive book illustrates creative ways to use the tools and libraries in MRDS so you can start building innovative new robotics applications. The book begins with a brief overview of MRDS and then launches into MRDS concepts and takes a look at fundamental code patterns that can be used in MRDS programming. You'll work through examples—all in C#—of common tasks, including an examination of the physics features of the MRDS simulator. As the chapters progress, so does the level of difficulty and you'll gradually evolve from navigating a simple robot around a simulated course to controlling simulated and actual robotic arms, and finally, to an autonomous robot that runs with an embedded PC or PDA. What you will learn from this book How to program in the multi-threaded environment provided by the concurrency and coordination runtime Suggestions for starting and stopping services, configuring services, and packaging your services for deployment Techniques for building new services from scratch and then testing them

How to build your own simulated environments and robots using the Visual Simulation Environment What robots are supported under MRDS and how to select one for purchase Who this book is for This book is for programmers who are interested in becoming proficient in the rapidly growing field of robotics. All examples featured in the book are in C#, which is the preferred language for MRDS.

Robotics in Education - Wilfried Lepuschitz 2018-09-01

This proceedings volume comprises the latest achievements in research and development in educational robotics presented at the 9th International Conference on Robotics in Education (RiE) held in Qawra, St. Paul's Bay, Malta, during April 18-20, 2018. Researchers and educators will find valuable methodologies and tools for robotics in education that encourage learning in the fields of science, technology, engineering, arts and mathematics (STEAM) through the design, creation and programming of tangible artifacts for creating personally meaningful objects and addressing real-world societal needs. This also involves the introduction of technologies ranging from robotics platforms to programming environments and languages. Extensive evaluation results are presented that highlight the impact of robotics on the students' interests and competence development. The presented approaches cover the whole educative range from elementary school to the university level in both formal as well as informal settings.

Elements of Robotics - Mordechai Ben-Ari 2017-10-25

This open access book bridges the gap between playing with robots in school and studying robotics at the upper undergraduate and graduate levels to prepare for careers in industry and research. Robotic algorithms are presented formally, but using only mathematics known by high-school and first-year college students, such as calculus, matrices and probability. Concepts and algorithms are explained through detailed diagrams and calculations. Elements of Robotics presents an overview of different types of robots and the components used to build robots, but focuses on robotic algorithms: simple algorithms like odometry and feedback control, as well as algorithms for advanced topics like localization, mapping, image processing, machine learning and swarm robotics. These algorithms are demonstrated in simplified contexts that enable detailed computations to be performed and feasible activities to be posed. Students who study these simplified demonstrations will be well prepared for advanced study of robotics. The algorithms are presented at a relatively abstract level, not tied to any specific robot. Instead a generic robot is defined that uses elements common to most educational robots: differential drive with two motors, proximity sensors and some method of displaying output to the user. The theory is supplemented with over 100 activities, most of which can be successfully implemented using inexpensive educational robots. Activities that require more computation can be programmed on a computer. Archives are available with suggested implementations for the Thymio robot and standalone programs in Python.

Trends in Intelligent Robotics, Automation, and Manufacturing - S.G. Poonambalam 2012-11-28

This book constitutes the proceedings of the First International Conference on Intelligent Robotics and Manufacturing, IRAM 2012, held in Kuala Lumpur, Malaysia, in November 2012. The 64 revised full papers included in this volume were carefully reviewed and selected from 102 initial submissions. The papers are organized in topical sections named: mobile robots, intelligent autonomous systems, robot vision and robust, autonomous agents, micro, meso and nano-scale automation and assembly, flexible manufacturing systems, CIM and micro-machining, and fabrication techniques.

Mobility for Smart Cities and Regional Development - Challenges for Higher Education - Michael E. Auer 2022

This book presents recent research on interactive collaborative learning. We are currently witnessing a significant transformation in the development of education and especially post-secondary education. To face these challenges, higher education has to find innovative ways to quickly respond to these new needs. On the one hand, there is a pressure by the new situation in regard to the COVID pandemic. On the other hand, the methods and organizational forms of teaching and learning at higher educational institutions have changed rapidly in recent months. Scientifically based statements as well as excellent experiences (best practice) are absolutely necessary. These were the aims connected with the 24th International Conference on Interactive Collaborative Learning (ICL2021), which was held online by Technische Universität Dresden, Germany, on 22-24 September 2021. Since its beginning in 1998, this conference is devoted to new approaches in learning with a focus on collaborative learning in Higher Education. Nowadays, the ICL

conferences are a forum of the exchange of relevant trends and research results as well as the presentation of practical experiences in Learning and Engineering Pedagogy. In this way, we try to bridge the gap between 'pure' scientific research and the everyday work of educators. This book contains papers in the fields of Teaching Best Practices Research in Engineering Pedagogy Engineering Pedagogy Education Entrepreneurship in Engineering Education Project-Based Learning Virtual and Augmented Learning Immersive Learning in Healthcare and Medical Education. Interested readership includes policymakers, academics, educators, researchers in pedagogy and learning theory, schoolteachers, learning industry, further and continuing education lecturers, etc.

The LEGO MINDSTORMS EV3 Idea Book - Yoshihito Isogawa
2014-11-07

The LEGO® MINDSTORMS® EV3 Idea Book explores dozens of creative ways to build amazing mechanisms with the LEGO MINDSTORMS EV3 set. Each model includes a list of the required parts, minimal text, and colorful photographs from multiple angles so you can re-create it without the need for step-by-step instructions. You'll learn to build cars with real suspension, steerable crawlers, ball-shooters, grasping robotic arms, and other creative marvels. Each model demonstrates simple mechanical principles that you can use as building blocks for your own creations. Best of all, every part you need to build these machines comes in one LEGO set (#31313)!

Creative Projects with LEGO Mindstorms - Benjamin Erwin 2001
Demonstrates the creation of robots, kinetic works of art, toys, and robotic animals through the combination of plastic gears, pulleys, beams, bricks, axles, and connector pegs, with motors, sensors, and programmable LEGO bricks.

Building Robots with LEGO Mindstorms NXT - Mario Ferrari
2011-04-18

The Ultimate Tool for MINDSTORMS® Maniacs The new MINDSTORMS kit has been updated to include a programming brick, USB cable, RJ11-like cables, motors, and sensors. This book updates the robotics information to be compatible with the new set and to show how sound, sight, touch, and distance issues are now dealt with. The LEGO MINDSTORMS NXT and its predecessor, the LEGO MINDSTORMS Robotics Invention System (RIS), have been called "the most creative play system ever developed." This book unleashes the full power and potential of the tools, sensors, and components that make up LEGO MINDSTORMS NXT. It also provides a unique insight on newer studless building techniques as well as interfacing with the traditional studded beams. Some of the world's leading LEGO MINDSTORMS inventors share their knowledge and development secrets. You will discover an incredible range of ideas to inspire your next invention. This is the ultimate insider's look at LEGO MINDSTORMS NXT system and is the perfect book whether you build world-class competitive robots or just like to mess around for the fun of it. Featuring an introduction by astronaut Dan Barry and written by Dave Astolfo, Invited Member of the MINDSTORMS Developer Program and MINDSTORMS Community Partners (MCP) groups, and Mario and Giulio Ferrari, authors of the bestselling *Building Robots with LEGO Mindstorms*, this book covers: Understanding LEGO Geometry Playing with Gears Controlling Motors Reading Sensors What's New with the NXT? Building Strategies Programming the NXT Playing Sounds and Music Becoming Mobile Getting Pumped: Pneumatics Finding and Grabbing Objects Doing the Math Knowing Where You Are Classic Projects Building Robots That Walk Robotic Animals Solving a Maze Drawing and Writing Racing Against Time Hand-to-Hand Combat Searching for Precision Complete coverage of the new Mindstorms NXT kit Brought to you by the DaVinci's of LEGO Updated edition of a bestseller

Building Smart LEGO MINDSTORMS EV3 Robots - Kyle Markland
2018-04-04

Build and program smart robots with the EV3. Key Features Efficiently build smart robots with the LEGO MINDSTORMS EV3 Discover building techniques and programming concepts that are used by engineers to prototype robots in the real world This project-based guide will teach you how to build exciting projects such as the object-tracking tank, ultimate all-terrain vehicle, remote control race car, or even a GPS-navigating autonomous vehicle Book Description Smart robots are an ever-increasing part of our daily lives. With LEGO MINDSTORMS EV3, you can now prototype your very own small-scale smart robot that uses specialized programming and hardware to complete a mission. EV3 is a robotics platform for enthusiasts of all ages and experience levels that makes prototyping robots accessible to all. This book will walk you

through six different projects that range from intermediate to advanced level. The projects will show you building and programming techniques that are used by engineers in the real world, which will help you build your own smart robot. You'll see how to make the most of the EV3 robotics platform and build some awesome smart robots. The book starts by introducing some real-world examples of smart robots. Then, we'll walk you through six different projects and explain the features that allow these robots to make intelligent decisions. The book will guide you as you build your own object-tracking tank, a box-climbing robot, an interactive robotic shark, a quirky bipedal robot, a speedy remote control race car, and a GPS-navigating robot. By the end of this book, you'll have the skills necessary to build and program your own smart robots with EV3. What you will learn Understand the characteristics that make a robot smart Grasp proportional beacon following and use proximity sensors to track an object Discover how mechanisms such as rack-and-pinion and the worm gear work Program a custom GUI to make a robot more user friendly Make a fun and quirky interactive robot that has its own personality Get to know the principles of remote control and programming car-style steering Understand some of the mechanisms that enable a car to drive Navigate to a destination with a GPS receiver Who this book is for This book is for hobbyists, robotic engineers, and programmers who understand the basics of the EV3 programming language and are familiar with building with LEGO Technic and want to try some advanced projects. If you want to learn some new engineering techniques and take your experience with the EV3 to the next level, then this book is for you.

Programming Lego Mindstorms NXT - Owen Bishop 2008-06-16
A guide to programming a robot using NXT-G and Microsoft VPL includes ten robot-specific projects that demonstrate how to expand a robot's capabilities and is accompanied by a DVD containing e-text, programming code, and a link to an accompanying Web site.
Introduction to AI Robotics, second edition - Robin R. Murphy
2019-10-01

A comprehensive survey of artificial intelligence algorithms and programming organization for robot systems, combining theoretical rigor and practical applications. This textbook offers a comprehensive survey of artificial intelligence (AI) algorithms and programming organization for robot systems. Readers who master the topics covered will be able to design and evaluate an artificially intelligent robot for applications involving sensing, acting, planning, and learning. A background in AI is not required; the book introduces key AI topics from all AI subdisciplines throughout the book and explains how they contribute to autonomous capabilities. This second edition is a major expansion and reorganization of the first edition, reflecting the dramatic advances made in AI over the past fifteen years. An introductory overview provides a framework for thinking about AI for robotics, distinguishing between the fundamentally different design paradigms of automation and autonomy. The book then discusses the reactive functionality of sensing and acting in AI robotics; introduces the deliberative functions most often associated with intelligence and the capability of autonomous initiative; surveys multi-robot systems and (in a new chapter) human-robot interaction; and offers a "metaview" of how to design and evaluate autonomous systems and the ethical considerations in doing so. New material covers locomotion, simultaneous localization and mapping, human-robot interaction, machine learning, and ethics. Each chapter includes exercises, and many chapters provide case studies. Endnotes point to additional reading, highlight advanced topics, and offer robot trivia.

Education in & with Robotics to Foster 21st-Century Skills - Monica Malvezzi
2021-05-13

This book includes papers presented at the International Conference "Educational Robotics in the Maker Era - EDUROBOTICS 2020", Online, February 2021. The contributions cover a variety of topics useful for teacher education and for designing learning by making activities for children and youth, with an emphasis on modern low-cost technologies (including block-based programming environments, Do-It-Yourself electronics, 3D printed artifacts, the use of intelligent distributed systems, the IoT technology, and gamification) in formal and informal education settings. This collection of contributions (17 chapters and 2 short papers) provides researchers and practitioners the latest advances in educational robotics in a broader sense focusing on science, technology, engineering, arts, and mathematics (STEAM) education. Teachers and educators at any school level can find insights and inspirations into how educational robotics can promote technological interest and 21st-century skills: creativity, critical thinking, team working, and problem-solving with special emphasis on new emerging

making technologies.

European Robotics Symposium 2008 - Herman Bruyninckx
2008-02-12

At the dawn of the new millennium, robotics is undergoing a major transformation in scope and dimension. From a largely dominant industrial focus, robotics is rapidly expanding into the challenges of unstructured environments. Interacting with, assisting, serving, and exploring with humans, the emerging robots will increasingly touch people and their lives. The goal of the Springer Tracts in Advanced Robotics (STAR) series is to bring, in a timely fashion, the latest advances and developments in robotics on the basis of their significance and quality. It is our hope that the wider dissemination of research developments will stimulate more exchanges and collaborations among the research community and contribute to further advancement of this rapidly growing field. The European Robotics Symposium (EUROS) was launched in 2006 as an international scientific single-track event promoted by EURON, the European Robotics Network linking most of the European research teams since its inception in 2000. Since then, EUROS has found its parental home under STAR, together with the other thematic symposia devoted to excellence in robotics research: FSR, ISER, ISRR, WAFR.

Building Robots With Lego Mindstorms - Mario Ferrari 2001-12-06
Lego robots! Mindstorms are sweeping the world and fans need to learn how to programme them. Lego Mindstorms are a new generation of Lego Robots that can be manipulated using microcomputers, light and touch sensors, an infrared transmitter and CD-ROMs. Since Lego launched Lego Mindstorms in late 1998 sales have skyrocketed - with no sign of slowing down. Mindstorms have captured the imagination of adults and children alike, creating a subculture of Mindstorm enthusiasts around the world. The kits are now a staple part of engineering and computer science classes at many high profile Universities. Building Robots with Lego Mindstorms provides readers with a fundamental understanding of the geometry, electronics, engineering, and programming required to build your own robots. Mario and Giulio Ferrari are world-renowned experts in the field of Lego Mindstorms robotics, and in this book they share their unrivaled knowledge and expertise of robotics as well as provide a series of chapters detailing how to design and build the most exotic robots. Mario and Giulio also give detailed explanations of how to integrate Lego Mindstorms kits with other Lego programmable bricks such as Scout and Cybermaster, as well as with non-robotic Lego Technics models.

Robot 2019: Fourth Iberian Robotics Conference - Manuel F. Silva
2019-11-19

This book gathers a selection of papers presented at ROBOT 2019 - the Fourth Iberian Robotics Conference, held in Porto, Portugal, on November 20th-22nd, 2019. ROBOT 2019 is part of a series of conferences jointly organized by the SPR - Sociedade Portuguesa de Robótica (Portuguese Society for Robotics) and SEIDROB - Sociedad Española para la Investigación y Desarrollo en Robótica (Spanish Society for Research and Development in Robotics). ROBOT 2019 built upon several previous successful events, including three biannual workshops and the three previous installments of the Iberian Robotics Conference, and chiefly focused on presenting the latest findings and applications in robotics from the Iberian Peninsula, although the event was also open to research and researchers from other countries. The event featured five plenary talks on state-of-the-art topics and 16 special sessions, plus a main/general robotics track. In total, after a stringent review process, 112 high-quality papers written by authors from 24 countries were selected for publication.

Landscapes of Participatory Making, Modding and Hacking - Kenneth Y T Lim 2017-03-07

This book describes maker culture as it is manifested in particular socio-cultural contexts, and describes some of the underlying narratives behind the emergence of such cultures and hackerspaces. With reference to case studies, it invites a recasting of long-standing academic notions of industrialization, industrial location, urbanization, and regional divides. The volume approaches this emergent socio-cultural phenomenon from an academic perspective, and, as such, differs from existing studies in this field as it is the first to approach maker culture and makerspaces by tracing trajectories from academic literature. This will provide teachers and researchers with a more grounded foundation upon which to base their own work in this nascent, yet rapidly growing, field.

ODROID Magazine - 2015-07-01

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ODROID: Have Fun With This Blast From the Past 8 Linux Kernel Build Scripts: Tweak Your System 9 Android Gaming: Nubs' Adventure - Challenging and Enjoyable 2D Platformer 10 Linux Gaming: Rare Gaming Gems - Part 1 15 Android Gaming: Kung Fury Street Rage - The Best Worst Movie Ever Made on YouTube is Now the Best Worst Ripoff Game Ever 16 Android Development: Building Android Studio 19 Jodro: Java Library for Controlling the GPIO Pins of the ODROID-C1 20 Experience Peace: White Noise Generator 21 ODROID-C1 Music Stand: Jamming with Style 24 OS Spotlight: DietPi for ODROID-C1 30 Popcorn Time: A Media Lover's Dream 32 Meet an ODROIDian: Chris McMurrough, Robotics Expert

The Art of LEGO MINDSTORMS EV3 Programming - Terry Griffin
2014-10-01

With its colorful, block-based interface, The LEGO® MINDSTORMS® EV3 programming language is designed to allow anyone to program intelligent robots, but its powerful features can be intimidating at first. The Art of LEGO MINDSTORMS EV3 Programming is a full-color, beginner-friendly guide designed to bridge that gap. Inside, you'll discover how to combine core EV3 elements like blocks, data wires, files, and variables to create sophisticated programs. You'll also learn good programming practices, memory management, and helpful debugging strategies—general skills that will be relevant to programming in any language. All of the book's programs work with one general-purpose test robot that you'll build early on. As you follow along, you'll program your robot to: -React to different environments and respond to commands -Follow a wall to navigate a maze -Display drawings that you input with dials, sensors, and data wires on the EV3 screen -Play a Simon Says-style game that uses arrays to save your high score -Follow a line using a PID-type controller like the ones in real industrial systems The Art of LEGO MINDSTORMS EV3 Programming covers both the Home and Education Editions of the EV3 set, making it perfect for kids, parents, and teachers alike. Whether your robotics lab is the living room or the classroom, this is the complete guide to EV3 programming that you've been waiting for. Requirements: One LEGO MINDSTORMS EV3 Home OR Education set (#31313 OR #45544).

Robot Building for Beginners, Third Edition - David Cook
2015-09-02

"I wrote this book because I love building robots. I want you to love building robots, too. It took me a while to learn about many of the tools and parts in amateur robotics. Perhaps by writing about my experiences, I can give you a head start."--David Cook Robot Building for Beginners, Third Edition provides basic, practical knowledge on getting started in amateur robotics. There is a mix of content: from serious reference tables and descriptions to personal stories and humorous bits. The robot described and built in this book is battery powered and about the size of a lunch box. It is autonomous; that is, it isn't remote controlled. The book is broken up into small chapters, suitable for bedtime (or bathroom) reading. The characteristics and purposes of each major component (resistor, transistor, wire, and motor) are described, followed by a hands-on experiment to demonstrate. Not only does this help the reader to understand a particular piece, but it also prepares them with processes to learn new parts on their own. An appendix offers an introduction to 3D printing and parts of the robot can, as an alternative, be "printed" using a 3D printer. The master project of the book is a simple, entertaining, line-following robot.

Careers in Robotics - Carol Hand 2019-07-15

Robotics is one of the most exciting career fields of the twenty-first century. This stimulating volume introduces readers to robotics makerspaces and describes how student makerspace experiences and robotics competitions can lead to a career in robotics. It captures the breadth of the robotics industry, describing recent robotics research in home control, medicine, industry, and the military and outlines the skills, education, and degrees required to work in robotics, and the process of finding a robotics job. Informative profiles of several makerspaces as well as day-in-the-life scenarios of roboticists in the space program and the service industry, among others, will keep readers engaged.

Beginning Robotics Programming in Java with LEGO Mindstorms - Wei Lu 2016-11-15

Discover the difference between making a robot move and making a robot think. Using Mindstorms EV3 and LeJOS—an open source project for Java Mindstorms projects—you'll learn how to create Artificial Intelligence (AI) for your bot. Your robot will learn how to problem solve, how to plan, and how to communicate. Along the way, you'll learn about classical AI algorithms for teaching hardware how to think; algorithms that you can then apply to your own robotic inspirations. If you've ever

wanted to learn about robotic intelligence in a practical, playful way, Beginning Robotics Programming in Java with LEGO Mindstorms is for you. What you'll learn: Build your first LEGO EV3 robot step-by-step Install LeJOS and its firmware on Lego EV3 Create and upload your first Java program into Lego EV3 Work with Java programming for motors Understand robotics behavior programming with sensors Review common AI algorithms, such as DFS, BFS, and Dijkstra's Algorithm Who this book is for: Students, teachers, and makers with basic Java programming experience who want to learn how to apply Artificial Intelligence to a practical robotic system.

The Art of LEGO MINDSTORMS NXT-G Programming - Terry Griffin 2010

The Art of LEGO MINDSTORMS NXT-G Programming teaches you how to create powerful programs using the LEGO MINDSTORMS NXT programming language, NXT-G. You'll learn how to program a basic robot to perform tasks such as line following, maze navigation, and object detection and how to combine programming elements (known as blocks) to create sophisticated programs. Author Terry Griffin covers essential functions like movement, sensors, and sound as well as more complex NXT-G features like synchronizing multiple operations. Because it's common for programs to not work quite right the first time they are run, a section of the book is dedicated to troubleshooting common problems including timing, sensor calibration, and proper debugging. Throughout the book, you'll learn best practices to help eliminate frustration when programming your robotic creations. This book is perfect for anyone with little to no previous programming experience who wants to master the art of NXT-G programming.

Programming Lego Mindstorms NXT - Owen Bishop 2011-04-18

Teach your robot new tricks! With this projects-based approach you can program your Mindstorms NXT robot to solve a maze, build a house, run an obstacle course, and many other activities. Along the way you will learn the basics of programming structures and techniques using NXT-G and Microsoft VPL. For hobbyists, and students working on robot projects, Bishop provides the background and tools to program your robot for tasks that go beyond the simple routines provided with the robot kit. The programs range in complexity from simple contact avoidance and path following, to programs generating some degree of artificial intelligence * a how-to guide for programming your robot, using NXT-G and Microsoft VPL * ten robot-specific projects show how to extend your robot's capabilities beyond the manufacturer's provided software. Examples of projects include: Maze solver, Robot House Builder, Search (obstacle avoidance), Song and Dance Act * flowcharts and data flow diagrams are used to illustrate how to develop programs * introduces basic programming structures

Robotics in Education - Munir Merdan 2019-08-06

This proceedings book gathers the latest achievements and trends in research and development in educational robotics from the 10th International Conference on Robotics in Education (RiE), held in Vienna, Austria, on April 10-12, 2019. It offers valuable methodologies and tools for robotics in education that encourage learning in the fields of science, technology, engineering, arts and mathematics (STEAM) through the design, creation and programming of tangible artifacts for creating personally meaningful objects and addressing real-world societal needs. It also discusses the introduction of technologies ranging from robotics platforms to programming environments and languages and presents

extensive evaluations that highlight the impact of robotics on students' interests and competence development. The approaches included cover the entire educative range, from the elementary school to the university level in both formal and informal settings.

User Interface Design for Virtual Environments: Challenges and Advances - Khan, Badrul 2011-12-31

The design of various virtual environments should be based on the needs of a diverse population of users around the globe. Interface design should be user centric and should strive for making the user's interaction as simple, meaningful, and efficient as possible. User Interface Design for Virtual Environments: Challenges and Advances focuses on challenges that designers face in creating interfaces for users of various virtual environments. Chapters included in this book address various critical issues that have implications for user interface design from a number of different viewpoints. This book is written for professionals who want to improve their understanding of challenges associated with user interface design issues for globally-dispersed users in various virtual environments.

Learn Robotics Programming - Danny Staple 2021-02-12

Develop an extendable smart robot capable of performing a complex series of actions with Python and Raspberry Pi Key Features Get up to speed with the fundamentals of robotic programming and build intelligent robots Learn how to program a voice agent to control and interact with your robot's behavior Enable your robot to see its environment and avoid barriers using sensors Book Description We live in an age where the most complex or repetitive tasks are automated. Smart robots have the potential to revolutionize how we perform all kinds of tasks with high accuracy and efficiency. With this second edition of Learn Robotics Programming, you'll see how a combination of the Raspberry Pi and Python can be a great starting point for robot programming. The book starts by introducing you to the basic structure of a robot and shows you how to design, build, and program it. As you make your way through the book, you'll add different outputs and sensors, learn robot building skills, and write code to add autonomous behavior using sensors and a camera. You'll also be able to upgrade your robot with Wi-Fi connectivity to control it using a smartphone. Finally, you'll understand how you can apply the skills that you've learned to visualize, lay out, build, and code your future robot building projects. By the end of this book, you'll have built an interesting robot that can perform basic artificial intelligence operations and be well versed in programming robots and creating complex robotics projects using what you've learned. What you will learn Leverage the features of the Raspberry Pi OS Discover how to configure a Raspberry Pi to build an AI-enabled robot Interface motors and sensors with a Raspberry Pi Code your robot to develop engaging and intelligent robot behavior Explore AI behavior such as speech recognition and visual processing Find out how you can control AI robots with a mobile phone over Wi-Fi Understand how to choose the right parts and assemble your robot Who this book is for This second edition of Learn Robotics Programming is for programmers, developers, and robotics enthusiasts who want to develop a fully functional robot and leverage AI to build interactive robots. Basic knowledge of the Python programming language will help you understand the concepts covered in this robot programming book more effectively.